

Bunching Near Transition in the AGS

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January 1998

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Jan. 14, 1998

Abstract

The proton driver for the muon collider must produce short pulses of protons in order to facilitate muon cooling and operation with polarized beams. In order to test methods of producing these bunches we have operated the AGS near transition and studied procedures which involved moving the transition energy, γ_t , to the beam energy. We were able to produce stable bunches of $3 - 5 \times 10^{12}$ protons with RMS widths of $\sigma = 2.2 - 2.7$ ns for longitudinal bunch areas of 1.5 eV-s, in addition to making measurements of the lowest two orders of the momentum compaction factor.

1 Introduction

Muon collider designs [1][2] require that the pions from which muons are produced are generated in a short bunch, both to facilitate subsequent cooling and to improve the separation between polarization states. Calculations done for the Feasibility Study imply that the required initial rms bunch length from the proton driver [3] is $\sigma \sim 1 - 2$ ns, roughly a factor of three shorter than the natural bunch length in the Brookhaven AGS [4]. Several ways of producing short bunches were considered in that study, including bunch expansion followed by rf bunch rotation [5], rebunching at a higher frequency

[6], operation near transition where the bunch length is naturally short [2], or the use of specialized linacs, beamlines, and bunching rings [7].

Since the proton driver contemplated for the muon collider could have its extraction energy near the natural transition energy [8], and would probably use a flexible momentum compaction (FMC) [9] lattice with easily adjustable transition energy, we have looked at options which could make use of transition in bunching. This paper summarizes simulations and experiments on the AGS near transition.

2 Bunching Near Transition

Although a number of methods of bunching are possible, the primary methods which have been considered for the proton driver of the muon collider are: 1) adiabatic spreading of the bunch followed by bunch rotation, 2) rebunching the beam at a higher frequency, and 3) energy spreading near transition, followed by a partial rf bunch rotation with the transition energy moved far enough from the beam energy to insure that the bunch rotation was fast. Combinations of these methods, for example bunch rotations in two successive synchrotrons have also been considered. Of these methods, 1) and 2) are comparatively common and well understood, but 3) involves operation near transition, which is comparatively uncommon. A recent development is the invention of the FMC lattice, which permits control of the transition energy over a very wide range, with minimal interactions with the rest of the machine. Calculations have shown that the transition energy can be changed by factors of 2 by a small adjustment of two quadrupoles, without changing the tunes of the machine [10].

Bunching near transition is complicated by the nonlinearity in phase shear which introduces nonlinear motion in synchrotron space, as well as the small value of $|\eta|$ which reduces the synchrotron frequency, making these nonlinearities more prominent. Following reference [11], the expression for the circumference

$$C(\delta) = C_0[1 + \alpha_0\delta(1 + \alpha_1\delta + \alpha_2\delta^2) + \dots] \quad (1)$$

where $\Delta p/p = \delta$, and C_0 is the median circumference ($\delta = 0$), and the α 's are various orders of the momentum compaction. One also defines the slip factor as a function of the revolution time T

$$\eta \equiv \frac{\Delta T}{T}/\delta \quad (2)$$

giving the transition gamma,

$$\gamma_t(\delta) = \gamma_{t0}[1 - (\alpha_1 + 0.5 - \alpha_0/2)\delta + O(\delta^2)] \quad (3)$$

and

$$\eta(\delta) \sim 1/\gamma_t^2 - 1/\gamma^2 + (1/\gamma_t^2)(\alpha_1 + 1.5\beta)\delta + O(\delta^2). \quad (4)$$

The first order momentum compaction is therefore

$$\alpha_1 = -\frac{1}{\gamma_{t0}} \frac{d\gamma_t}{d\delta} - 1/2 + \alpha_0/2 \quad (5)$$

In the equations above, γ_t is the transition energy, $\alpha_0 = 1/\gamma_t^2$, $\gamma = E/m_p$, E is the total energy, $\beta = v/c = 0.993$ for this test, m_p is the proton mass, and the subscript 0 refers to the nominal beam energy. Far from transition the difference between the first two terms of equation (4) dominates and $\eta(\delta)$ is essentially a constant, however close to transition, the first two terms cancel each other and $\eta(\delta) \propto \delta$. Since the shear or slip in synchrotron space, (δ, ϕ) , is equal to $\eta\delta$, if both η and δ depend linearly on momentum, the product is quadratic. Thus the general bunch deformation is a shear in the ϕ direction which depends quadratically on δ within the bunch. If η can be made constant over the range of δ in the bunch, by requiring $\alpha_1 = -1.5$, the quadratic deformation will be removed. The $O(\delta^2)$ term is assumed to be small, since it is difficult to design precise measurements even of the linear term.

A plot of the γ_t against δ as a function of sextupole and octupole settings using MAD [12], Figure 1, shows that it is, in principle, possible to match $d\gamma_t/d\delta$ of the machine to the beam over a large range of bunch momenta, although the capability of MAD to compute the higher orders of momentum compaction may be questionable. With sextupoles off η decreases with δ , however the slope $d\gamma_t/d\delta$, and the quadratic component, increases with horizontal sextupole current I_{Hs} . The quadratic component can be canceled with octupoles. Predictions of the effect of sextupole and octupole correctors on the momentum dependence of γ_t might not correspond to the real AGS behavior due to the large orbit distortions from the γ_t jump.

The longitudinal space charge voltage V_{sc} seen by a beam particle is proportional to the slope of the current density dI_p/dz . It becomes important if the bunching is done slowly, in n turns, since the distortion of the bunch is due to $V_{sc}n$, however it seems possible to reduce these problems if the final bunching is done in a few turns [13]. Since space charge effects depend on the

derivative of a roughly symmetric charge distribution, they result in a shear of the bunch in the δ direction which has a linear or cubic dependence on ϕ . The effects of transition and space charge are shown in Figure 2, where a) shows the effects of nonlinear phase shear $\eta\delta$, and b) shows the effect of space charge, which tends to modulate the energy of the bunch with a term proportional to dI_p/dz . These simulations were done by tracking the longitudinal motion of particles in the machine using ESME [14].

In this experiment, bringing the γ_t down to the beam γ lowers the synchrotron frequency, making the bucket much higher. As the suddenly mismatched bunch rotates in the taller bucket, it becomes taller and narrower in phase, ϕ , or time. As one moves closer to transition one would expect to find a narrower final bucket, however the synchrotron frequency can become so low that bunching would not occur at all.

3 Operation of the AGS

The operating mode of the AGS is shown in Figure 3. The maximum beam energy was reduced from the normal 28 GeV to around 7 GeV by shortening the acceleration period, and the γ_t jump system [14] was modified to give a short flattop period before the transition energy dropped. The beam was flattopped for 300 ms before the magnet guide field was raised slightly and then ramped down. One bunch was injected from the booster at about 0.08 sec into the acceleration cycle, when $dB/dt \sim 0.4$ T/s, and the beam was in the machine for about 500 ms total. The rf cavities were operated at 340 kV/turn while there was beam. The bunch current was $3 - 5 \times 10^{12}$ in a single bunch, and the bunch area was measured to be 1.5 ± 0.05 eV-s, declining during the cycle. Measurements of bunch area were made by reconstructing the bunch shape by observing the development of the bunch area during synchrotron rotations, the data are shown as a function of time from injection in Figure 4.

Previous work had shown that the γ_t jump system caused significant changes in the nonlinear momentum compaction factor α_1 , the measured maximum dispersion and the momentum aperture. Although three sextupole families are present in the ring, the locations of these sextupoles are such that these lattice changes are difficult to modify both before and after the transition energy is moved. In order to evaluate the magnitude of these effects we remeasured the transition energy as a function of radial position by

measuring beam loss as a function of phase-switch delay time and horizontal sextupole current.

4 Experimental Results

The transition energy was first measured relative to the gauss clock, which gives the instantaneous field in the dipoles as a function of time, for four values of radial displacement. The published value of α_1 was checked by measuring the radial dependence of beam losses as a function of the time at which the phase of the rf accelerating field was flipped, to compensate for the reversed direction of shear.

The measurements were made by accelerating the beam through transition with the transition jump off, and minimizing beam loss by varying the time the rf phase is switched. These data were taken as a function of the horizontal position of the beam and also horizontal sextupole current. During these measurements, low emittance beam was used, and the radial position of the beam scanned over the range ± 4.6 mm. The measurements were repeated at sextupole currents of 0 and 100 A. The results of these measurements are shown in Figure 5a and b.

The transition energy is obtained from the average of values with the sextupoles on, and is equal to $\gamma_t = 8.34 \pm 0.05$. The corresponding measurements of α_1 obtained using equation (5) above give the results $\alpha_1 = 7.2 \pm 1.5$ with $I_{H_s} = 0$ A, and $\alpha_1 = 3.5 \pm 1.5$ with $I_{H_s} = 100$ A. These measurements agree roughly with earlier published data [15], however time constraints did not permit good statistics. The parameters of the operating machine are also likely to slowly evolve over time as it is tuned for a variety of experiments. There may also be a systematic error in the measurement of γ_t by this method due to the optimum time delay between the phase flip and transition time, because of the nonlinear and asymmetric behavior of the bunches near transition.

When the operating mode described in Figure 3 was implemented, the beam was found to be quite stable near transition. After the first quadrupole synchrotron oscillation all structure tended to damp out and the beam circulated stably without significant losses or beam blowup. Changes in the beam energy, to move below or above transition, or sextupole settings seemed to make little difference and the overall structure of the beam was almost unaffected by accelerator parameters. Losses were not accurately recorded, but

seemed small, $\sim 5\%$, and no particular effort was made to minimize them.

Our data, an example of which is shown in Figure 6, consist primarily of peak beam current and instantaneous current plotted against machine phase (mountain range) plots from 10 ms before the end of the γ_t jump to 40 ms after, using the wall current monitor [17]. The data were read into a LeCroy 9350 digital oscilloscope controlled by LABVIEW, and the data was digitized at intervals of 1 ns. Measurements were made over a range of $0.97 < \gamma/\gamma_t < 1.02$. Some data were taken showing debunching at the end of the run. The bandwidth of the system was determined by cable attenuation.

Measurements of the bunch shape as a function of time were used to measure the synchrotron period and synchrotron frequency, which was then used to estimate γ_t . The result of these measurements was $\gamma_t = 8.43 \pm 0.05$, with the error calculated from the scatter of the individual measurements. A typical set of data used to determine the synchrotron period is shown in Figure 7.

The results of bunching tests are shown in Figure 8, where the bunch shape is plotted both before and after the γ_t was suddenly changed. The narrow final shape is noticeably asymmetric because it was impossible to entirely tune out the chromatic effects mentioned above. Runs further from transition showed a number of synchrotron oscillations and the bunch length in later minima was always longer than the first minimum. Closer to transition the bunch length contracted to a minimum and then expanded to roughly the initial value. There seemed to be little emittance blowup. Losses were a function of sextupole currents, but there was insufficient time to explore the dependence in detail. Although the minimum bunch width decreased with increasing sextupole current, it was found that the sextuples required only about half of the current predicted by MAD to optimize $\eta(\delta)$, and we were not able to produce a value of $\alpha_1 = -1.5$, which is expected to produce the minimum bunch length.

The initial bunch shape could be approximated either with a gaussian with an rms width of $\sigma \sim 9$ ns, or a two dimensional polynomial of the form

$$\rho(\delta, \phi) \propto 1 - [(\phi/\phi_{max})^2 + (\delta/\delta_{max})^2]^{(1.75 \pm 0.25)}, \quad (6)$$

which is projected onto the time axis to give a slightly more peaked profile. The shape after bunching tended to be somewhat asymmetric, as would be expected if α_1 was not optimized. There were no dipole oscillations and phase mismatch seemed negligible.

The final bunch width was, of course, a function of the bunch dimensions before the γ_t jump was turned off. In one run, the initial bunch length was increased which produced less momentum spread. This was done by pumping the longitudinal coherent quadrupole mode by modulating the amplitude of the rf voltage at twice the synchrotron frequency. The modulation was a 320 Hz square wave of 20 % amplitude synchronized so the bunch was longest when the γ_t jump was fired. When the γ_t jump was turned off, the bunch rotated in the normal way, but the uncorrected width was $\sigma = 2.2$ ns, about 15% shorter than bunches obtained without the rf modulation. (The fitted bunch width depended on how much of the wings of the bunch were fitted). This bunch is shown as Figure 9; we anticipate that optimization would produce even shorter bunches.

The fitted shape shown in Figure 8 contains corrections for attenuation loss in the cables. This attenuation can be detected in a number of ways, including a small ($\sim 5\%$) bunch width dependence of the total bunch area, which occurs primarily in higher frequency components. This correction was made by Fourier analyzing the measured bunch shape, correcting the individual Fourier coefficients for attenuation loss, then summing the series to produce a corrected final bunch shape. The corrections were obtained from the tabulated attenuation properties of the cable from the wall current monitor to the control room of the AGS. This final shape required an initial bunch width about 5% less than that obtained by fitting the uncorrected data.

In order to examine $\eta\delta$ more directly, we also measured debunching when V_{RF} was suddenly reduced to zero. This was done at two energies to be sensitive to $\eta(\gamma)$. The data, shown in Figure 8, have sharp discontinuities at the ends of the bunch which make the determination of the boundaries fairly unambiguous. An asymmetry of the bunch shape as it lengthens is consistent with $\alpha_1 \neq -1.5$. Simulations described can be used to determine values for η and γ_t from estimates of the full momentum spread of the beam. If the full width of the bunch is assumed to be $\delta = 0.025$, obtained from simulations below, debunching data give a value of $\gamma_t = 8.45 \pm 0.04$, which is consistent with other methods, but more indirect.

We assume that the beam induced voltage $V = I_b Z$, where $I_b < 100$ A is the beam current and the impedance of the vacuum chamber, $Z \sim 100 \Omega$, is small compared with the voltage required to contain the bunch in a bucket. As the bunch spreads, the instantaneous current and the induced voltage become very small and this assumption become more exact.

5 Discussion

In order to understand the mechanism of bunching we have done simulations using ESME [14]. These calculations track the longitudinal motion of particles in the bunch over the acceleration and bunching cycle with various parameters. The primary variables are $\Delta\gamma = \gamma_t - \gamma$ and α_1 . Simulations show that bunching can occur over a period of 1 ms and produce bunches with large momentum spread (full widths of $\delta = 0.024$) and narrow widths. An example of these simulations are shown in Figure 10, which approximates the parameters shown in Figure 7. These simulations fairly closely match the structure of the data, however the accuracy of the fit seems to be a function of a number of variables such as the parameterization of the density of charge within a bunch. The shape of the shortest bunch that can be produced is sensitive to α_1 and can be used to estimate this parameter, however the bunch shapes seen do not precisely match those produced in simulations, perhaps indicating higher order terms, ($\eta \propto \delta^2$). The data are consistent with $\alpha_1 = 0.0 \pm 1.0$. The total height of the bunch, $\delta \sim 0.024$, can circulate in the AGS which has a total momentum acceptance of $\delta \sim \pm 0.025$. Since the momentum acceptance is sufficiently large, we expect a further reduction in the bunch length is possible, however this might be accompanied with increased losses, if the beams were large.

The measurements of γ_t and α_1 by a variety of methods are generally consistent with previous measurements, which give $\gamma_t = 8.45$, $\alpha_1 = 2.5$ from Wei et. al. [16] and $\gamma_t = 8.49$ from MAD. It should be noted that all the measurements are somewhat indirect and the real machine parameters may vary somewhat from the models. We assume that the most accurate method of measuring γ_t is by means of the synchrotron frequency, since systematic errors should be small and the measurements are comparatively straightforward.

A proton bunch width of $\sigma \sim 2.2 - 2.7$ ns begins to be short enough to consider the use of this method for the proton driver of the muon collider. The measurements here imply that α_1 is perhaps somewhat larger than previously measured and more sextupole and octupole currents would permit smaller values of $\eta(\delta)$ which would, in turn, produce shorter bunches. These data show some of the shortest bunches ever measured in the AGS.

While space charge effects are much smaller here than they would be for the proton driver, it is assumed that the use of FMC lattices would allow very fast motion of the transition energy, which could make bunching fast

enough so that this effect might not significantly perturb bunching, even for much higher currents. One could also jump above transition, where space charge would help bunching, or insert inductance into the ring to compensate the effect.

While the measurements made here apply directly to the design of a proton driver for a muon collider, the stability of high current bunches close to transition is also relevant to the design of isochronous rings for other applications.

6 Conclusions

During a short run, we were able to explore the operation of the AGS when it was flattoped close to transition. It was found that the bunch length could be reduced by a factor of ~ 3 by using the γ_t jump system to suddenly drop the transition energy to the beam energy, and the beam seemed fairly stable during this exercise. We also measured γ_t using: 1) the time of phase flip, 2) the synchrotron frequency, and 3) debunching time, producing rough agreement with previous measurements and with MAD calculations for the lattice. Measurements of α_1 generally agreed with earlier data, but the precision of the data were limited by statistics and measurement time. Attempts to tune α_1 with sextupoles and octupoles were less successful due to power supply limitations. The stability of the beam circulating near transition was unexpected, and argues for the stability of high current isochronous storage rings

We were unable to systematically explore possible methods of bunch manipulation due to time constraints, nevertheless, the $\sigma \sim 2.2$ ns bunch length produced by this method is sufficiently short to be useful for the proton driver of the muon collider. A further reduction by another factor of 30% would be even more desirable and this might be obtained by means of the methods tested here. Modification of the bunch shape before rotation, for example, seems useful, but was not optimized. Effects of space charge were also not studied systematically, and measurements with significant space charge effects would be highly desirable, as would the ability to move the transition energy in two directions, which could be used to produce rapid bunching.

7 Acknowledgments

We would like to thank the operating crew of the AGS for their cooperation performing these measurements. We would also like to acknowledge useful discussions with C. Johnstone, D. Neuffer of Fermilab, M. Yoshi and Y. Mori of KEK, and B. Autin of CERN.

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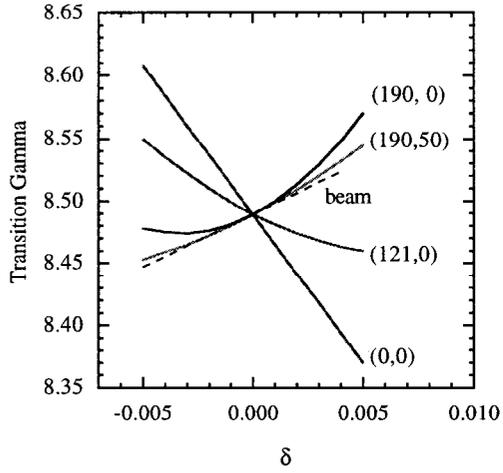


Figure 1: Predicted momentum dependence of γ_t as a function of horizontal sextupole and octupole current, (I_{H_s}, I_O) .

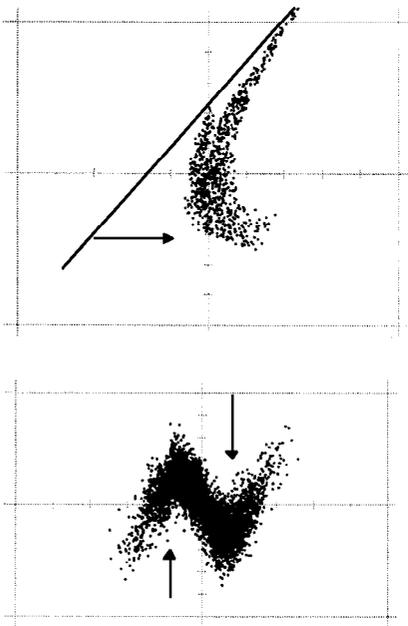


Figure 2: Effects of nonlinear η and space charge on the final phase space distributions, a) shows the effect of a quadratic horizontal shear which occurs when $\alpha_1 = -1.5$, and b) shows the effect of vertical shear from strong space charge effects. The plots span a phase space area of ± 100 MeV and ± 40 ns.

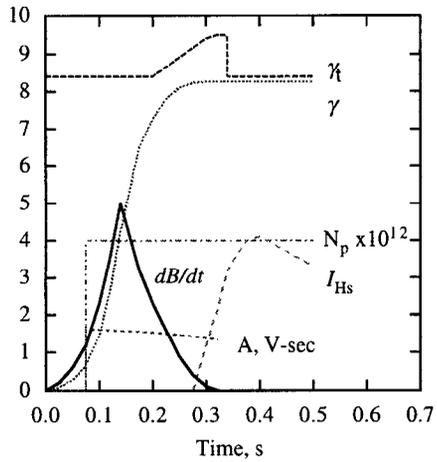


Figure 3: The operating mode of the AGS, showing the magnet ramp dB/dt , beam gamma, γ , transition gamma, γ_t , sextupole currents, I_{Hs} , and longitudinal bunch area, A .

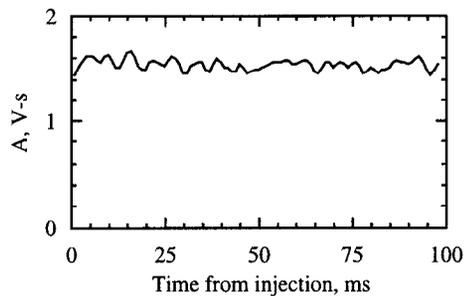


Figure 4: Bunch area as a function of time from injection.

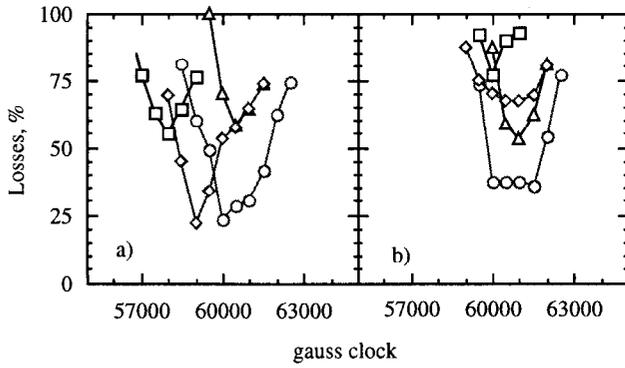


Figure 5: Losses going through transition as a function of the time at which the phase of the rf is flipped, and machine field B . Here squares, diamonds, circles and triangles refer to $\Delta r = 4.6, 1.5, -1.5, -4.6$ mm respectively, a) $I_{H_s} = 0$, b) $I_{H_s} = 100A$.

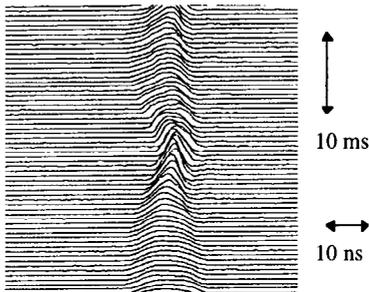


Figure 6: Mountain range plot of the bunch after the transition energy was dropped to the beam energy.

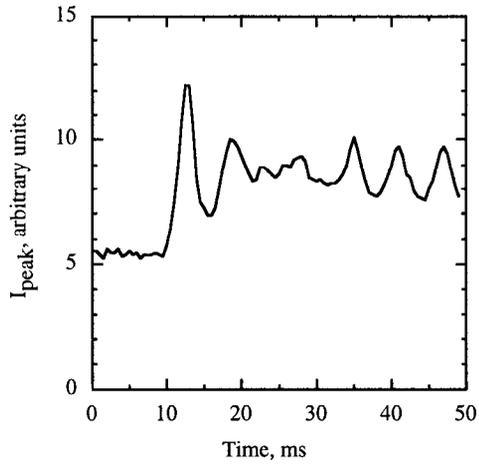


Figure 7: Peak current as a function of time in the acceleration cycle. Bunching starts at 8 ms.

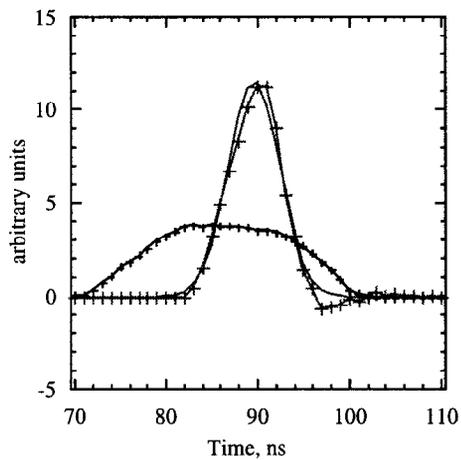


Figure 8: Bunch shapes before and after bunching (crosses) showing a final corrected bunch length of $\sigma = 2.66$ ns for a 1.5 V-s bunch together with the fitted Gaussian curve (dashed line).

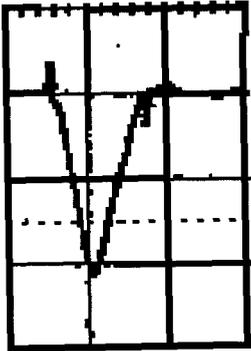


Figure 9: Bunching with pulsed rf and the γ_t jump, giving $\sigma \sim 2.2$ ns (uncorrected) and 11.95 ns full width. Horizontal scale is 10 ns/div, vertical scale is arbitrary.

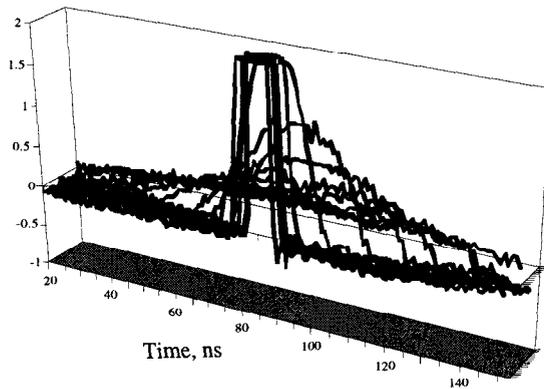


Figure 10: Debunching of the beam when V_{rf} is set to 0 after the beam is bunched.

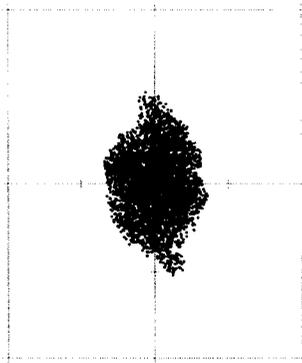


Figure 11: The final phase space after δ_t is moved close to the beam energy ($\gamma = 8.40$). Area shown is $\Delta t = \pm 15$ ns, $\delta = \pm 0.02$